

Reactmine-2: a Statistical Beam Search Algorithm for Learning Biochemical Reactions from Time Series Data

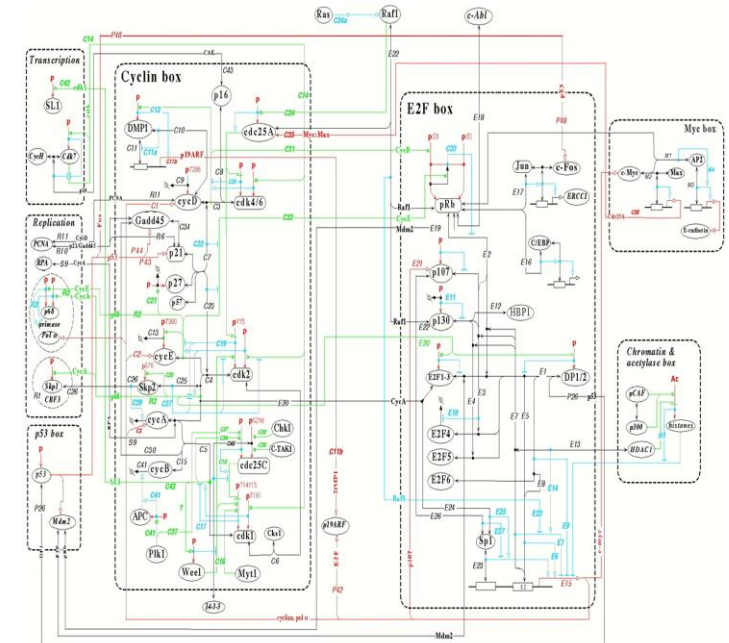
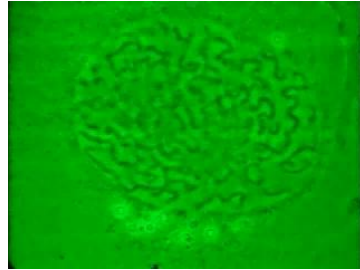
Constant Le Bezvoët, François Fages, Julien Martinelli

Lifeware group <http://lifeware.inria.fr/>
on Computational Systems Biology and Optimization

INRIA Saclay, Palaiseau, France

A Computer Scientist View at Cell Biology: Cells Compute

- Cells process signals
- Regulate their metabolism
- Take decisions such as
 - Replication
 - Migration
 - Differentiation
 - Apoptosis (suicide)
- Control those processes



Chemical Reaction Networks (CRN)

➤ What are the programs ?

Continuous time, continuous protein concentrations: **analog computation**

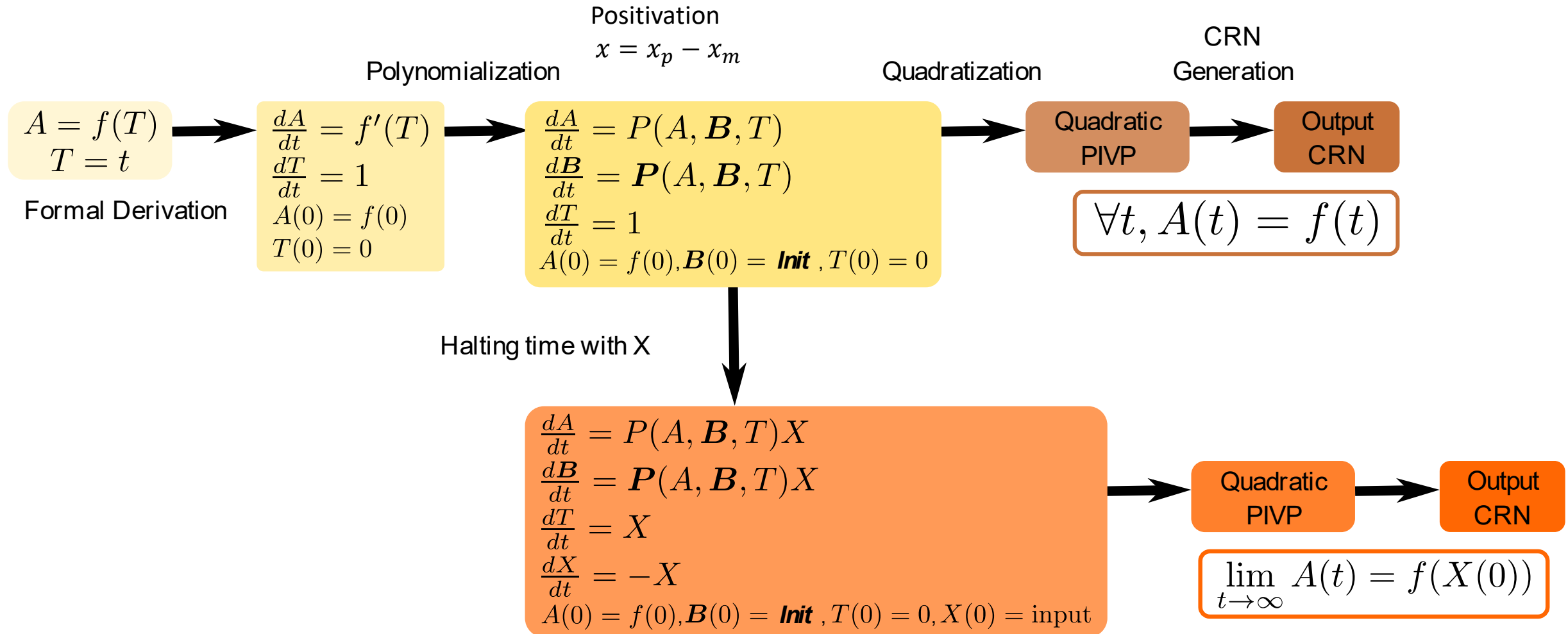
➤ Computational Systems Biology: development of CRN models of cell processes

- Repositories of thousands of hand-made CRN models, e.g. biomodels.net
- Model building tools, e.g. BIOCHAM, using graph-theoretic, symbolic computation and constraint solving methods
- Need for Machine Learning methods to infer CRN reactions from experimental data

➤ Computational Synthetic Biology: design CRNs to implement new functions

Turing Completeness of CRNs and BIOCHAM Compilation Pipeline

[Fages Le Guludec Bournez Pouly CMSB 2017] [Fages Hemery Soliman ACM CCA 2025]



CRN Syntax and *Hierarchy of Semantics*

CRN: reaction rules with kinetics

$k1 \cdot A \cdot B$ for $A + B \Rightarrow 2 \cdot B$

$k2 \cdot A$ for $A \Rightarrow 2 \cdot A$

$k3 \cdot B$ for $B \Rightarrow _$

- ODE semantics:
$$\frac{dB}{dt} = k1 \cdot A \cdot B - k3 \cdot B$$
$$\frac{dA}{dt} = k2 \cdot A - k1 \cdot A \cdot B$$

- Stochastic semantics (continuous time Markov chain):

- Discrete (Petri net)

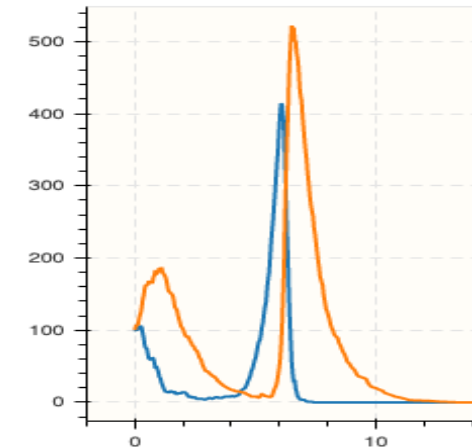
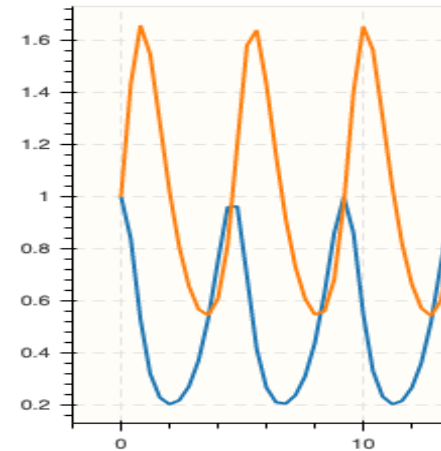
- Boolean semantics:

```
list_stable_states.
```

```
[A-0,B-0]  
[A-1,B-0]
```

```
generate_ctl_not.
```

```
reachable(stable(A))  
reachable(stable(notA))  
reachable(stable(notB))  
reachable(steady(B))
```

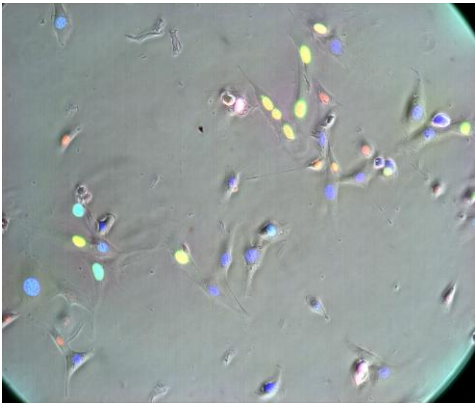


Learning Protocol:

Infer Reactions with Kinetics from Experimental/Simulation Traces

Input: prior knowledge and finite traces,
i.e. set of observed state transitions (velocity matrix)

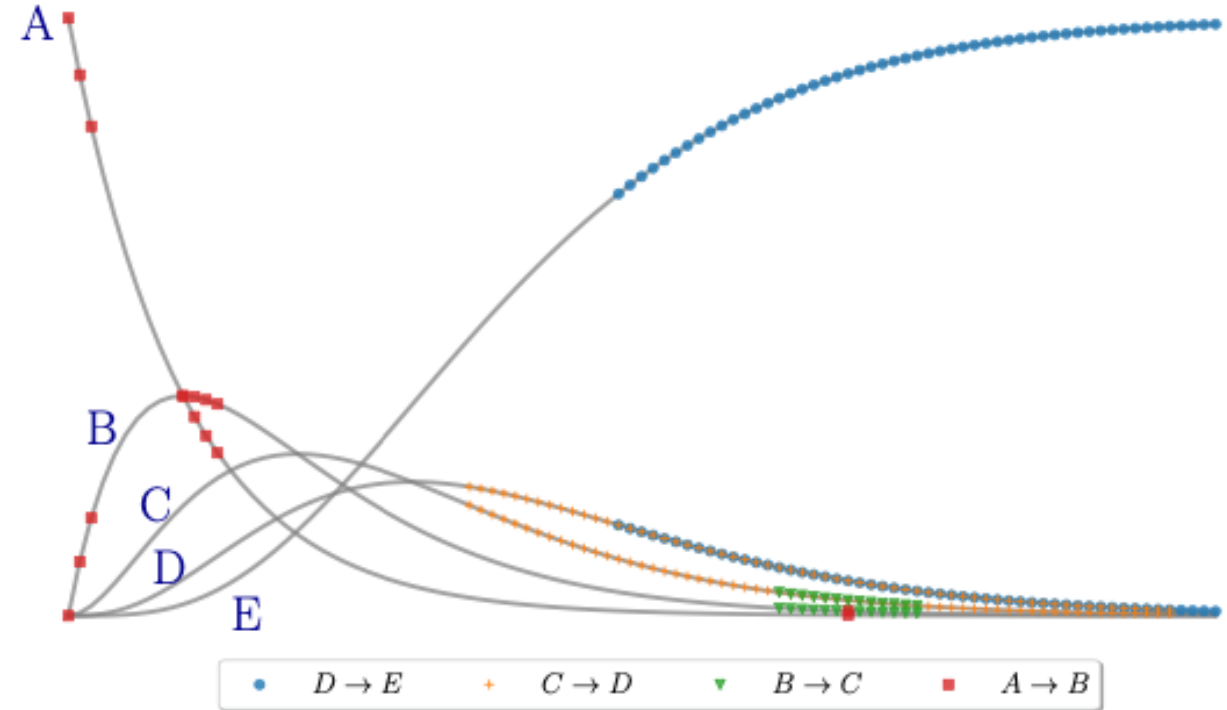
- time evolution of molecular species concentrations
- coming from biological experiments



Fluorescence videomicroscopy
C. Feillet F. Delaunay 2013

- or from simulations of a hidden CRN

Output: CRN, i.e. finite set of kinetic reactions

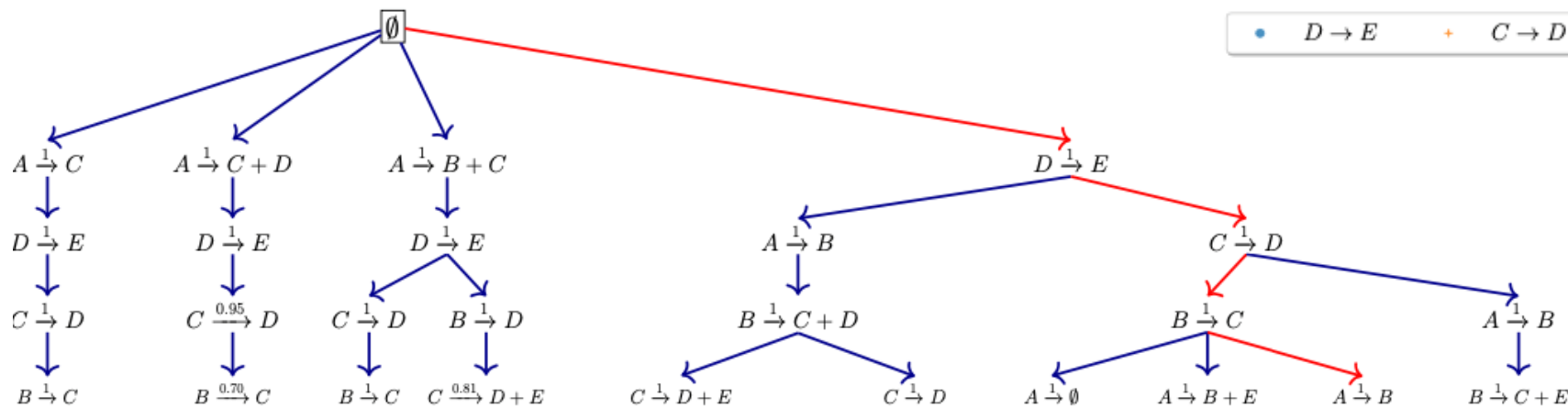
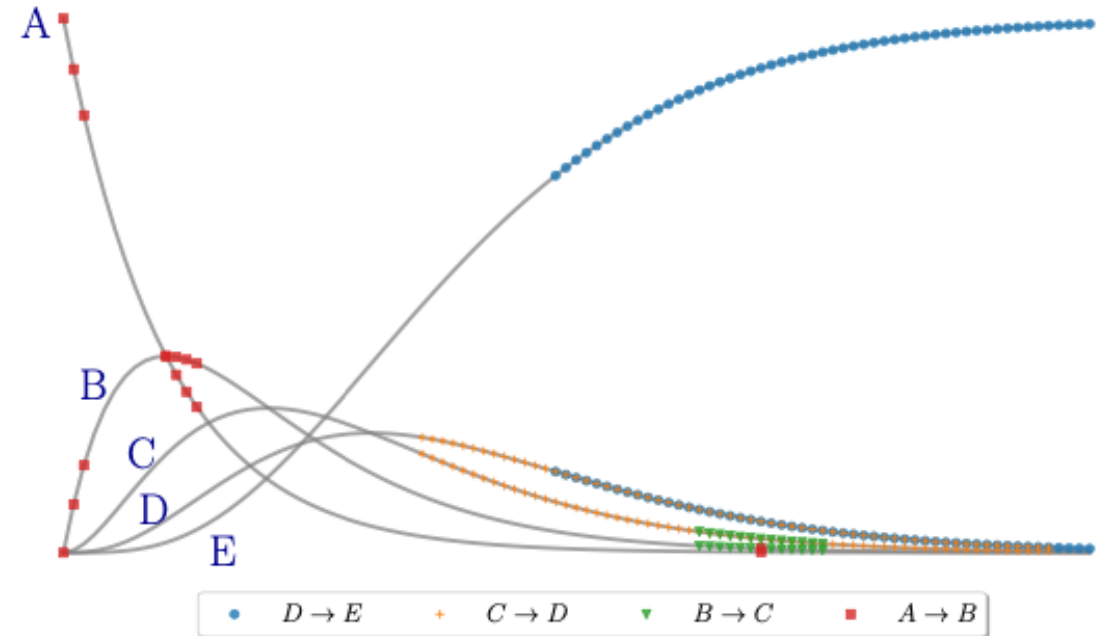


Reactmine Statistical Tree Search Algorithm

Sequential inference of reactions with kinetics;

1. on some **transition support** where the preponderant changes can be paired in one **preponderant reaction**;
2. **ranked by kinetics of lowest variance**;
3. trace update by subtraction of the inferred reaction;

Final global kinetic parameter re-optimization



Inference of both Reaction's Structure and Kinetics

At each node of the search tree with **bounded depth** $\leq \gamma$ (i.e. maximum number of reactions to infer)

1) For each observed transition consider all **reaction skeletons** on **concentration changes with highest velocities**

$$i_l^{\max} = \underset{i}{\operatorname{argmax}} |\tilde{v}_{l,i}| \quad \tilde{v}_{l,i} = \frac{\hat{v}_{l,i}}{\max_{1 \leq k \leq n} |\hat{v}_{k,i}|} \quad R_\delta(t_l) = \left\{ i \in \{1, \dots, m\}, \hat{v}_{l,i} < 0, \left| \frac{\hat{v}_{l,i}^{\max}}{\hat{v}_{l,i}} \right| \leq \delta \right\} \quad \text{with } \text{velocity ratio} \leq \delta$$

$$P_\delta(t_l) = \left\{ i \in \{1, \dots, m\}, \hat{v}_{l,i} > 0, \left| \frac{\hat{v}_{l,i}^{\max}}{\hat{v}_{l,i}} \right| \leq \delta \right\}$$

2) Rank reaction candidates (k, R, P) according to **kinetic variance** $\hat{\sigma}_j = \frac{1}{|T(r)|} \sum_{l \in T(r)} \left(\frac{|v_{l,j}|}{\prod_{i \in R} y_{l,i}} - \hat{k}_j \right)^2$

on their supporting transitions $T(r) = \{l \in \{1, \dots, n\} \mid \exists \delta \in [1, \delta_{\max}], r^\delta(t_l) = (R, P)\}$

3) Create successor nodes for **least kinetic variance candidates** with **beam width** $\leq \beta$
and subtract reaction effect on the trace

Finally, re-optimize the inferred kinetic parameters on the whole trace $\mathbf{k} = \underset{\mathbf{k} \in \mathbb{R}_+^p}{\operatorname{argmin}} \|\mathbf{V} - \mathbf{F}(\mathbf{Y}, \mathbf{k})\mathbf{S}\|_F^2$

SINDy Non-Linear Sparse Regression Algorithm

Brunton, S. L., Proctor, J. L., and Kutz, J. N. (2016). Discovering governing equations from data by sparse identification of nonlinear dynamical systems. *Proceedings of the National Academy of Sciences*, pages 3932–3937.

- Reconstructs an **ODE system** from transition traces, **as weighted sums of library functions**

$$\mathbf{V} = \Theta(\mathbf{Y})\Xi \quad (9)$$

$\Theta(\mathbf{Y}) \in \mathbb{R}^{n \times p}$ is a library of p functions constructed from the input variables $\mathbf{Y}$ including, for instance, first to m -order polynomial interactions, e.g. $\mathbf{Y}_{\bullet,j} \odot \mathbf{Y}_{\bullet,j'}$, the sin and cos functions, e.g. $\sin(\mathbf{Y}_{\bullet,j})$, or even more sophisticated user-defined functions. The dynamics of each variable is then captured by a weighted combination of library members, the weights being encompassed in Ξ . Because it is thought that the expression of the dynamics should be sparse within the library $\Theta(\mathbf{Y})$, SINDy proposes to obtain Ξ using sparse regression.

$$\Xi = \underset{\Xi \in \mathbb{R}^{p \times m}}{\operatorname{argmin}} \|\mathbf{V} - \Theta(\mathbf{Y})\Xi\|_F^2 + \lambda \|\Xi\|_1 \quad (10)$$

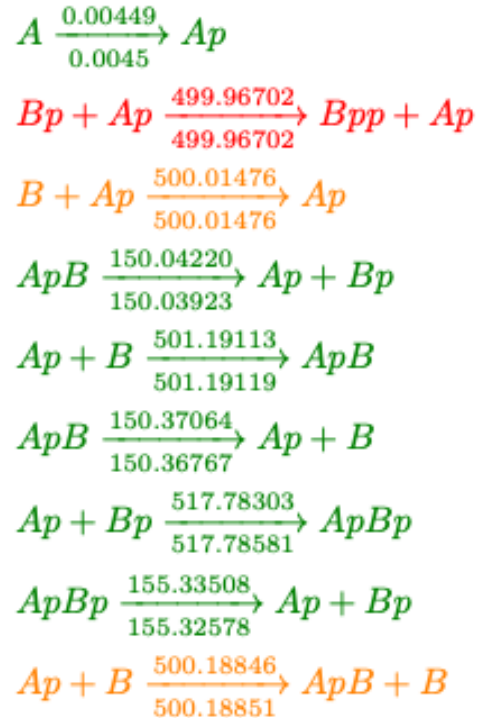
- Ensures **sparsity** by $\|\cdot\|_1$ regularization (Lasso regression)
- One single hyperparameter λ .

Results compared to SINDy on Simple CRN with One Single Trace

Name	Hidden CRN	CRN inferred by Reactmine	ODE system inferred by SINDy
Chain	$A \xrightarrow{1} B$	$D \xrightarrow[1.00041]{0.99869} E$	$\begin{cases} \dot{A} = -1.00A \\ \dot{B} = 1.00A - 1.00B \\ \dot{C} = 1.03B - 1.03C + 0.01D - 0.06AB \\ \dot{D} = 0.33B - 0.64DE \\ \dot{E} = 1.00D \end{cases}$
	$B \xrightarrow{1} C$	$C \xrightarrow[1.00071]{0.99836} D$	
	$C \xrightarrow{1} D$	$B \xrightarrow[0.99753]{1.00102} C$	
	$D \xrightarrow{1} E$	$A \xrightarrow[1.00107]{1.00069} B$	
Loop	$A \xrightarrow{1} B$	$A \xrightarrow[1.00005]{0.99958} B$	$\begin{cases} \dot{A} = -1.00A + 1.03E - 0.006D - 0.07AE - 0.06DE \\ \dot{B} = 1.00A - 1.00B + 0.004C + 0.001AB - 0.211AC - 0.092BC \\ \dot{C} = 1.14B - 1.18C - 0.002D - 0.17AB + 0.39CD \\ \dot{D} = 0.35B - 0.35E \\ \dot{E} = 0.39C + 0.457E - 4.21AE \end{cases}$
	$B \xrightarrow{1} C$	$B \xrightarrow[0.99243]{0.99748} C$	
	$C \xrightarrow{1} D$	$C \xrightarrow[0.99156]{0.99772} D$	
	$D \xrightarrow{1} E$	$D \xrightarrow[0.92045]{0.99771} E$	
	$E \xrightarrow{1} A$	$E \xrightarrow[1.00007]{0.99758} A$	
Reactant Parallel	$A + C \xrightarrow{3} B + C$	$D \xrightarrow[1.97698]{2.00109} C$	$\begin{cases} \dot{A} = -1.12A - 510000276790.32C - 0.87AB + 1.03AD \\ \quad + 510000276788.57AC + 510000276790.32BC - 0.04DC \\ \dot{B} = 1.12A + 510000276790.24C + 0.87AB - 1.04AD \\ \quad - 510000276788.49AC - 510000276790.24BC + 0.04DC \\ \dot{C} = -2.20D + 0.02E - 0.19AD + 0.40DE \\ \dot{D} = 0.07A + 1.96D + 1.02E - 0.06DE \\ \dot{E} = -1.00E \end{cases}$
	$D \xrightarrow{2} C$	$E \xrightarrow[0.00526]{1.00101} C$	
	$E \xrightarrow{1} C$	$A + C \xrightarrow[2.95790]{2.94380} B + C$	
Product Parallel	$A + C \xrightarrow{1} B + C$	$C \xrightarrow[3.12657]{2.93602} E$	$\begin{cases} \dot{A} = -0.93C \\ \dot{B} = 0.93C \\ \dot{C} = 68364.34 - 84189.93A + 32887.73C + 14190.64D \\ \quad + 21285.97E - 17066.849AC - 40273.85AE + 990.87CD \\ \quad + 990.83CD + 1486.24CE + 7919.89DE \\ \dot{D} = 3.73C - 1.84AC \\ \dot{E} = 65012.55A - 60751.24C - 77885.60E - 4258.48AC \\ \quad - 10214.65CE - 27068.38DE \end{cases}$
	$C \xrightarrow{2} D$	$C \xrightarrow[2.08438]{1.95735} D$	
	$C \xrightarrow{3} E$	$A + C \xrightarrow[1.04002]{0.96372} B + C$	

Results on MAPK Signalling CRN with One Single Trace

Reactmine



SINDy

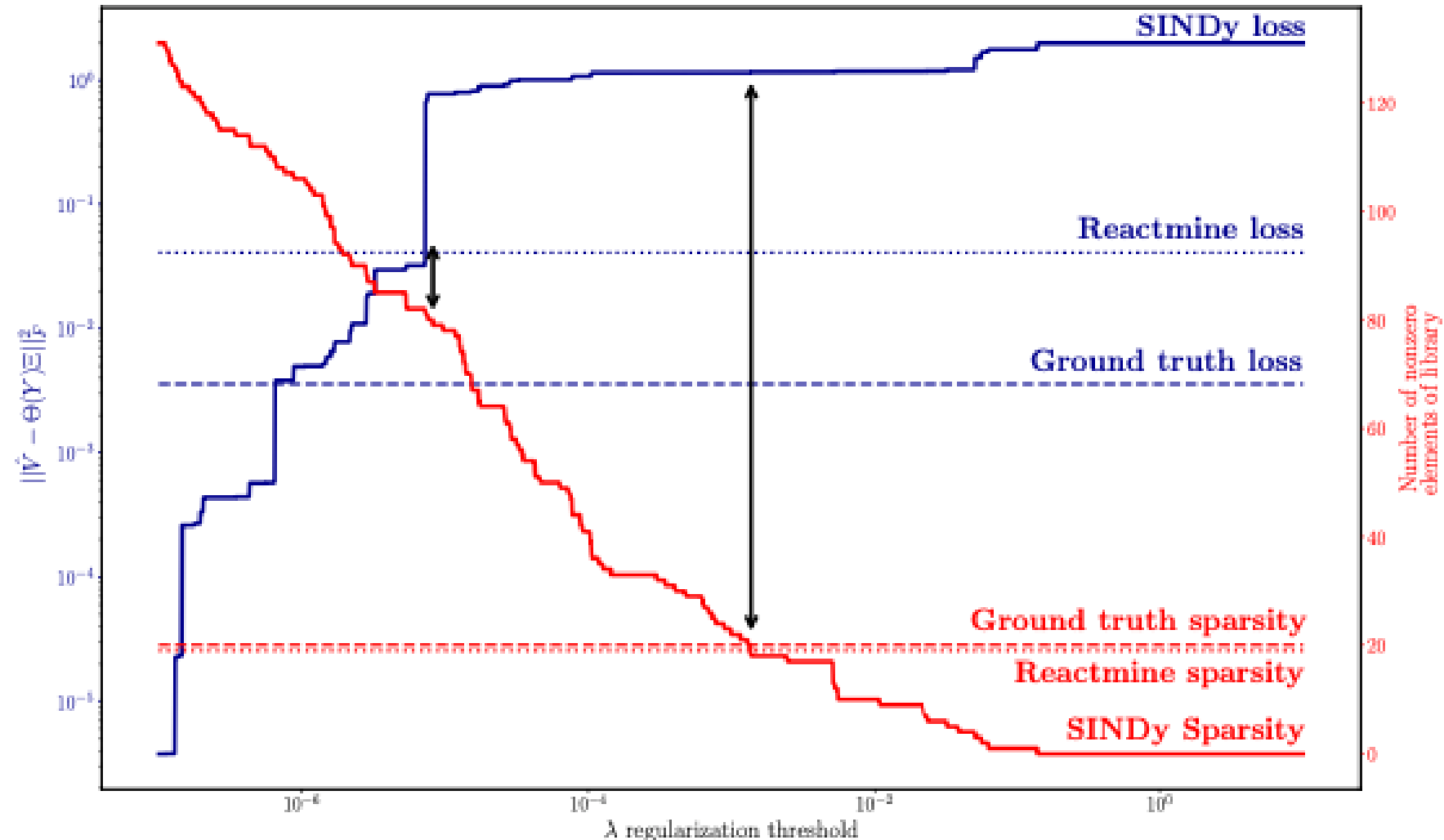
$$\begin{aligned}
 \dot{Bpp} &= 11764.89 - 9818.81Bpp - 21809.21Ap - 64774.82ApBp - 9881.63Bp \\
 &\quad + 109653.06ApB - 10102.57B - 23028.83A + 23087.90Bpp \times Ap \\
 &\quad + 47383.24Bpp \times ApBp + 0.01Bpp \times Bp - 94598.54Bpp \times ApB \\
 &\quad + 0.05Bpp \times B + 24104.25Bpp \times A + 58119.14Ap \times Bp \\
 &\quad + 117674.08Ap \times B + 68314.42ApBp \times Bp + 239788.36ApBp \times B \\
 &\quad - 171491.97Bp \times ApB + 0.03Bp \times B + 45027.82Bp \times A + 118690.34B \times A \\
 \dot{Ap} &= 0.003Bp - 0.001Bpp \times Bp - 0.004Bpp \times B - 0.002Bp \times B \\
 \dot{ApBp} &= -0.002Bp + 0.001Bpp \times Bp + 0.004Bpp \times B + 0.002Bp \times B \\
 \dot{Bp} &= -11345.814 + 9469.53Bpp + 20253.98Ap + 62939.32ApBp \\
 &\quad + 9525.97Bp - 105529.77ApB + 9401.39B + 22299.11A \\
 &\quad - 21772.25Bpp \times Ap - 45730.13Bpp \times ApBp - 0.01Bpp \times Bp \\
 &\quad + 91003.53Bpp \times ApB - 0.05Bpp \times B - 23476.51Bpp \times A \\
 &\quad - 56249.34Ap \times Bp + 996.55Ap \times B - 64537.43ApBp \times Bp \\
 &\quad - 113908.83ApBp \times B + 163092.38Bp \times ApB - 0.03Bp \times B \\
 &\quad - 42276.50Bp \times A + 113704.11ApB \times B - 763.549B \times A \\
 \dot{ApB} &= 0 \\
 \dot{B} &= -668.78 + 557.83Bpp + 1724.07Ap + 2552.29ApBp \\
 &\quad + 564.79Bp - 5063.51ApB + 551.20B + 784.94A \\
 &\quad - 1609.99Bpp \times Ap + -1960.37Bpp \times ApBp - 0.001Bpp \times Bp \\
 &\quad + 4399.19Bpp \times ApB - 0.01Bpp \times B - 827.38Bpp \times A \\
 &\quad - 3441.84Ap \times Bp + 543.68Ap \times B - 4279.75ApBp \times Bp \\
 &\quad - 8537.02ApBp \times B + 10869.45Bp \times ApB - 0.003Bp \times B \\
 &\quad - 3146.138Bp \times A + 6610.523ApB \times B + 1384.463B \times A \\
 \dot{A} &= 0
 \end{aligned}$$

Reaction $Ap + B \xrightarrow{1000} ApB$ inferred with 3 algebraically equivalent reactions $Ap + B \xrightarrow{500} Ap \mid ApB \mid ApB + B$

Reaction $ApBp \xrightarrow{150} Ap + Bpp$ replaced by $Ap + Bp \xrightarrow{500} Ap + Bpp$ which is a good approximation:

direct production without intermediary complex leading to similar simulation traces

No sparse ODE system with a good loss function is inferred for any value of λ



Correctness of Lasso Regression [Yu Zhao 2006]

The Lasso estimates $\hat{\beta}^n(\lambda)$ are defined by $\hat{\beta}^n(\lambda) = \underset{\beta \in \mathbb{R}^p}{\operatorname{argmin}} \{ \|Y_n - X_n \beta\|_2^2 + \lambda \|\beta\|_1 \}$

For $\lambda = 0$, $p \geq n$ and X_n of full rank we have a closed form solution $\hat{\beta} = (X_n^T X_n)^{-1} X_n^T Y_n$

Let $X_n(1), X_n(2)$ be the columns of X_n multiplied by non-zero, zero β coefficients and $C^n = \frac{1}{n} X_n X_n^T$

The (low correlation) **Strong irrepresentable Condition** is $\left| C_{21}^n (C_{11}^n)^{-1} \operatorname{sign}(\beta_{(1)}^n) \right| < 1$. $C^n = \begin{pmatrix} C_{11}^n & C_{12}^n \\ C_{21}^n & C_{22}^n \end{pmatrix}$
 Implied by **low correlations between covariates in the model and not in the model**

Theorem (Sufficient condition for **correctness of Lasso model selection with exponential rate in n**)

For fixed q and p , and under regularity conditions (1) and (2), Lasso is strongly sign consistent if the Strong Irrepresentable Condition holds. That is, when Strong Irrepresentable Condition holds, $\forall \lambda_n$ that satisfies $\frac{\lambda_n}{n} \xrightarrow{n} 0$ and $\frac{\lambda_n}{n^{(1+c)/2}} \xrightarrow{n} +\infty$ with $0 < c < 1$, we have :

$$\mathbb{P}(\hat{\beta}^n(\lambda_n) =_s \beta) = 1 - \mathcal{O}(\exp(-n^c))$$

Where the conditions (1) and (2) are : $C^n \xrightarrow{n} C$ $\frac{1}{n} \max_{1 \leq i \leq n} ((x_i^n)^\top x_i^n) \xrightarrow{n} 0$

Multi-traces on Different Initial Conditions with Zeros

To make SinDy work, we concatenate m traces stemming from different initial conditions. The resulting input matrix when the library function is the products of concentrations is of the form:

$$\Theta(X_n) = \begin{bmatrix} x_1^1(0) & x_2^1(0) & \cdots & x_1^1(0)x_2^1(0) & \cdots \\ x_1^1(\Delta t) & x_2^1(\Delta t) & \cdots & \cdots & \cdots \\ \vdots & \vdots & \ddots & \cdots & \cdots \\ x_1^1((n-1)\Delta t) & x_2^1((n-1)\Delta t) & \cdots & \cdots & \cdots \\ x_1^2(0) & x_2^2(0) & \cdots & x_1^2(0)x_2^2(0) & \cdots \\ \vdots & \vdots & \ddots & \cdots & \cdots \\ x_1^m((n-1)\Delta t) & x_2^m((n-1)\Delta t) & \cdots & \cdots & \cdots \end{bmatrix}$$

where: $x_k^i(l\Delta t)$ is the concentration of species k at time $l\Delta t$ on the i -th trace.

n is the number of time points

n_s is the number of species (used later)

Δt is the time step

Type 1 CRN: Atmost One Reactant per Reaction on Multitraces with 1 Non-zero Initial Concentrations

Proposition

For a CRN of type 1, suppose we concatenate the traces as above and choose the optimal library function. Suppose also that the time step is such that $\Delta T =_{n \rightarrow \infty} o(\frac{1}{n})$. Then Zhao's irrepresentable condition holds for a big enough n where n is the number of time points.

Proof

$$\begin{aligned}
 C_{1,1}^n(i, j) &= \frac{1}{nm} \sum_{k=1}^m \sum_{l=0}^{n-1} X_i^k(l\Delta T) X_j^k(l\Delta T) \\
 &= \frac{1}{m} \sum_{k=1}^m \frac{1}{n} \langle X_i^k, X_j^k \rangle \\
 &= \mathbb{E}_m \left[\frac{1}{n} \langle X_i^k, X_j^k \rangle \right] \\
 C_{1,1}^n &\xrightarrow{n \rightarrow \infty} I_p \quad (C_{1,1}^n)^{-1} \xrightarrow{n \rightarrow \infty} I_p \\
 C_{2,1}^n(i, j) &\xrightarrow{n \rightarrow \infty} \mathbb{E}_m [X_{a_i}^k(0) X_{b_j}^k(0)] \quad C_{2,1}^n(i, j) \xrightarrow{n \rightarrow \infty} 0 \quad |C_{2,1}^n (C_{1,1}^n)^{-1} \beta^1| < 1 \text{ for large enough } n
 \end{aligned}$$

$$\begin{aligned}
 \frac{1}{n} \langle X_i^k, X_j^k \rangle &= \frac{1}{n} \sum_{l=0}^{n-1} X_i^k\left(\frac{l}{n^2}\right), X_j^k\left(\frac{l}{n^2}\right) \text{ by Cesaro lemma} \\
 &\xrightarrow{n \rightarrow \infty} X_i^k(0), X_j^k(0) \\
 C_{1,1}^n(i, j) &\xrightarrow{n \rightarrow \infty} \mathbb{E}_m [X_i^k(0) X_j^k(0)] \text{ by dominated convergence theorem}
 \end{aligned}$$

Type 2 CRN: At most 2 Reactants per Reaction on Multitraces with 2 Non-zero Initial Conditions

Multitraces with at most two non-zero initial conditions

$$C = \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 & 0 \\ 1 & 1 & 0 & \cdots & 0 & 0 \\ 1 & 0 & 1 & \cdots & 0 & 0 \\ \cdots & \cdots & \cdots & \ddots & \cdots & \cdots \\ 0 & 0 & 0 & \cdots & 1 & 1 \end{bmatrix}$$

if $C^n(i, j)$ has 3 or 4 species :

$$C_{i,j}^n \xrightarrow{n \rightarrow \infty} \mathbb{E}_m \left[X_{a_i}^k(0) X_{b_i}^k(0) X_{a_j}^k(0) \right] = 0$$

if $C^n(i, j)$ has 2 species :

$$C_{i,j}^n \xrightarrow{n \rightarrow \infty} \mathbb{E}_m \left[X_{a_i}^k(0)^{\epsilon_1} X_{a_j}^k(0)^{\epsilon_2} \right] = \frac{1}{m} = \frac{2}{n_s(n_s + 1)} \quad \epsilon_1, \epsilon_2 \in (1, 2)$$

if $C^n(i, j)$ has 1 specie :

$$C_{1,1}^n = \begin{bmatrix} A & D^\top \\ D & \frac{1}{m} I_{\frac{n_s(n_s-1)}{2}} \end{bmatrix}$$

Non-sparse covariance matrix

Yu & Zhao's correctness condition is not satisfied

SINDy Evaluation with Multitraces with 2 Non-zero Initial Conditions

Ground Truth		Simple trace		Multiple trajectories	
Equation	Rate	Equation	Rate	Equation	Rate
$A \rightarrow B$	1	$A \rightarrow B$	1.00	$A \rightarrow B$	1.00
$B \rightarrow C$	1	$B \rightarrow C$	1	$B \rightarrow C$	1.00
$C \rightarrow D$	1	$C \rightarrow D$	0.48	$C \rightarrow D$	1.00
$D \rightarrow E$	1	$D + E \rightarrow$	1.02	$D \rightarrow E$	1.06

Ground Truth		Simple trace		Multiple trajectories	
Equation	Rate	Equation	Rate	Equation	Rate
$A \rightarrow B$	1	$A \rightarrow B$	1.00	$A \rightarrow B$	1.00
$B \rightarrow C$	1	$B \rightarrow C$	1.00	$B \rightarrow C$	1.00
$C \rightarrow D$	1	$C \rightarrow D$	1.00	$C \rightarrow D$	1.00
$D \rightarrow E$	1	$D \rightarrow E$	1.00	$D \rightarrow E$	1.00
$E \rightarrow A$	1	$E \rightarrow A$	1.00	$E \rightarrow A$	1.00

Ground Truth		Simple trace		Multiple trajectories	
Equation	Rate	Equation	Rate	Equation	Rate
$A \rightarrow B$	1	$A \rightarrow B$	1.01	$A \rightarrow B$	1.01
$D \rightarrow C$	2			$D \rightarrow C$	1.99
$E \rightarrow C$	3			$E \rightarrow C$	3.01

Ground Truth		Simple trace		Multiple trajectories	
Equation	Rate	Equation	Rate	Equation	Rate
$A \rightarrow B$	1			$A \rightarrow B$	1.01
$C \rightarrow D$	2			$C \rightarrow D$	2.04
$C \rightarrow E$	3	$C + D \rightarrow E$	0.75	$C \rightarrow E$	3.06

Ground Truth		Single trace		Multiple trajectories	
Equation	Rate	Equation	Rate	Equation	Rate
$B + D \rightarrow E$	0.3			$B + D \rightarrow E$	0.3
$2A \rightarrow B$	0.1	$2A \rightarrow B + C$	0.20	$2A \rightarrow B$	0.1
$A \rightarrow C$	0.2	$A + E \rightarrow$	0.16	$A \rightarrow C$	0.2
$C \rightarrow D$	0.13	$C + D \rightarrow A$	0.09	$C \rightarrow D$	0.13

Conclusion and Perspectives

- State-of-the-art sparse regression algorithms such as Lasso and SINDy are provably correct under strong non-correlation hypotheses between dynamic library terms
 - Generally not satisfied on data time series obtained from one single initial state (wild type trace)
 - Proven satisfied here for monomolecular CRNs on multitraces from initial conditions with only one non zero
 - SINDy's ODE discovery algorithm uses
 - 1 single hyperparameter
 - May fail on single trace data from very simple CRN
 - Needs (unrealistic) multitraces obtained from initial states with many 0, shown to entail correctness of Lasso sparsity
- Reactmine variance-based tree search algorithm
 - Reduction to 1 main hyperparameter by recourse to beam search
 - Good results obtained on single simulation traces of a hidden CRN, e.g. cell signaling and cell cycle models
 - Applied to inference of main systemic regulators of circadian clocks in accordance to model-based analysis [Matinelli Dulong Li Teboul Soliman Levi F- Ballesta *Bioinformatics* 2021]
 - Applied to videomicroscopy data with inference of main conclusions of model-based analysis (upregulation of rev-erb during G2 phase) [Traynard Feillet Soliman Delaunay F- *Biosystem* 2016]
 - Challenge of learning unobserved variables: hopes by analysis of non-supported transitions.
- Not aware of good results obtained yet with LLM or GNN on such complex dynamical systems